Lecture 2a Wednesday, January 8, 2020 8:49 PM

<u>News:</u> The library has acknowledged receipt of my reserve list for the class, and is processing it. I will keep you posted

Reading

- Section 2.1
- Section 2.2 up to (but not including) the paragraph that starts "these subtle cases" on p57
- Section 2.3 & 2.4

Today: Vectors and Introduction to manifolds

VECTORS: Starting with material from Chapter 1 (Special relativity in Minkowski space) p17

Basis Elin parenthus =7 Write vector A as four four four four

A=A e(m)

Siven a curve X (2)

The taugent vector V(2) has components

 $V^{m} = \frac{dx^{n}}{dx}$

Under Lorentz transforms $\times^{\mu} \rightarrow \times^{\mu'} = \Lambda^{\mu'} \times^{\mu}$

- _1 µ × thus V' = Nu Va Learn how basis vectors transform by noting that the vector V is invariant: $V = V^{\mu} \hat{e}_{(\mu)} = V^{\nu'} \hat{e}_{(\nu')} = \Lambda^{\nu'}{}_{\mu} V^{\mu} \hat{e}_{(\nu')}.$ $= \sum_{(m)} e_{(m)} = \sum_{(m)} e_{(\nu')} e_{(\nu')}.$ (1.40)=) E(u) must transform as the inverse Lorentz transform. Notation: Brocrae of My witten as No (primes indicate the new coordinates and the primes switch places on the inverse)

DUAL VECTORS (Carroll section 1.5)

- If one wants to form an invariant (scalar) dot product, one of the vectors dotted needs to transform as the inverse Lorentz transform.
- Never worry about this with 3d rotations because

RT = R' for these

 Vectors that transform according to the inverse Lorentz transform are called "dual vectors" or "oneforms" written as

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 A basis for dual vectors has an upper index and is written:

(U)

• With the property

 $\mathcal{O}^{(\omega)}(\hat{e}_{(\mu)}) = \mathcal{O}_{\mu}^{(\nu)}$

• A simple dual vector is a gradient of a scalar

 $d\phi = \frac{\partial \phi}{\partial x^{n}} \hat{\phi}^{(n)}$ The components $\int d\phi$

Using the chain rule:

 $\frac{\partial \phi}{\partial x^{n'}} = \frac{\partial x^{n}}{\partial x^{n'}} \frac{\partial \phi}{\partial x^{n}}$ $= \int_{u'}^{u} \frac{\partial \phi}{\partial x^{n}}$ confirming the dual vector transformation